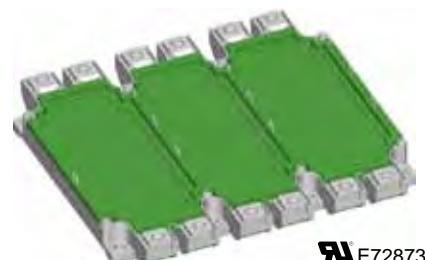
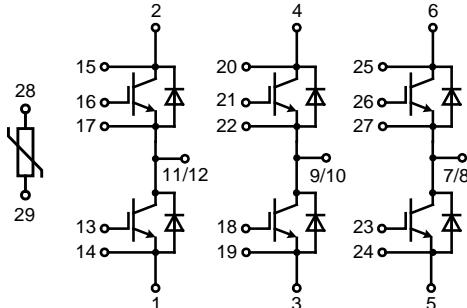


IGBT Modules

Sixpack

I_{C80} = 440 A
 V_{CES} = 1200 V
 $V_{CE(sat)\text{ typ.}}$ = 2.2 V



E72873

See outline drawing for pin arrangement

IGBTs

Symbol	Conditions	Maximum Ratings		
V_{CES}	$T_{VJ} = 25^\circ\text{C}$ to 125°C	1200		V
V_{GES}		± 20		V
I_{C25}	$T_C = 25^\circ\text{C}$	640		A
I_{C80}	$T_C = 80^\circ\text{C}$	440		A
RBSOA	$R_G = 2.7 \Omega$; $T_{VJ} = 125^\circ\text{C}$ Clamped inductive load; $L = 100 \mu\text{H}$	$I_{CM} = 900$		A
		$V_{CEK} \leq V_{CES}$		
t_{SC} (SCSOA)	$V_{CE} = 900 \text{ V}$; $V_{GE} = \pm 15 \text{ V}$; $R_G = 2.7 \Omega$ $T_{VJ} = 125^\circ\text{C}$; non-repetitive; $V_{CEmax} \leq V_{CES}$	10		μs
P_{tot}	$T_C = 25^\circ\text{C}$	2.2		kW

Symbol **Conditions**

Symbol	Conditions	Characteristic Values			
		($T_{VJ} = 25^\circ\text{C}$, unless otherwise specified)			
$V_{CE(sat)}$	$I_C = 450 \text{ A}$; $V_{GE} = 15 \text{ V}$	$T_{VJ} = 25^\circ\text{C}$		2.2	V
		$T_{VJ} = 125^\circ\text{C}$		2.5	V
$V_{GE(th)}$	$I_C = 18 \text{ mA}$; $V_{GE} = V_{CE}$		4.5		V
I_{CES}	$V_{CE} = V_{CES}$; $V_{GE} = 0 \text{ V}$	$T_{VJ} = 25^\circ\text{C}$		1	mA
		$T_{VJ} = 125^\circ\text{C}$		21	mA
I_{GES}	$V_{CE} = 0 \text{ V}$; $V_{GE} = \pm 20 \text{ V}$			600	nA
$t_{d(on)}$ t_r $t_{d(off)}$ t_f E_{on} E_{off}	Inductive load, $T_{VJ} = 125^\circ\text{C}$ $V_{CE} = 600 \text{ V}$; $I_C = 450 \text{ A}$ $V_{GE} = \pm 15 \text{ V}$; $R_G = 2.7 \Omega$		190		ns
			116		ns
			475		ns
			100		ns
			35		mJ
			47		mJ
C_{ies}	$V_{CE} = 25 \text{ V}$; $V_{GE} = 0 \text{ V}$; $f = 1 \text{ MHz}$		33		nF
Q_{Gon}	$V_{CE} = 600 \text{ V}$; $V_{GE} = 15 \text{ V}$; $I_C = 450 \text{ A}$		3.3		μC
R_{thJC}			0.057	K/W	

Features

- NPT³ IGBT technology
- low saturation voltage
- low switching losses
- square RBSOA, no latch up
- high short circuit capability
- positive temperature coefficient for easy parallelling
- MOS input, voltage controlled
- ultra fast free wheeling diodes
- solderable pins for PCB mounting
- package with copper base plate

Advantages

- space savings
- reduced protection circuits
- package designed for wave soldering

Typical Applications

- AC motor control
- AC servo and robot drives
- power supplies

Diodes

Symbol	Conditions	Maximum Ratings		
I_{F80}	$T_C = 80^\circ\text{C}$	450	A	
I_{FRM}	$t_p = 1 \text{ ms}$	900	A	
I^2t	$T_{VJ} = 125^\circ\text{C}; t = 10 \text{ ms}; V_R = 0 \text{ V}$	35000	A^2s	

Symbol **Conditions****Characteristic Values** $(T_{VJ} = 25^\circ\text{C}, \text{unless otherwise specified})$

		min.	typ.	max.	
V_F	$I_F = 450 \text{ A}; V_{GE} = 0 \text{ V}; T_{VJ} = 25^\circ\text{C}$			2.2	V
I_{RM}	$I_F = 450 \text{ A}; di_F/dt = 3500 \text{ A}/\mu\text{s}; T_{VJ} = 125^\circ\text{C}; V_R = 800 \text{ V}$		200		A
R_{thJC}			0.075		K/W

Temperature Sensor NTC

Symbol	Conditions	Characteristic Values		
		min.	typ.	max.
R_{25}	$T = 25^\circ\text{C}$	4.75	5.0	5.25
$B_{25/50}$			3375	$\text{k}\Omega/\text{K}$

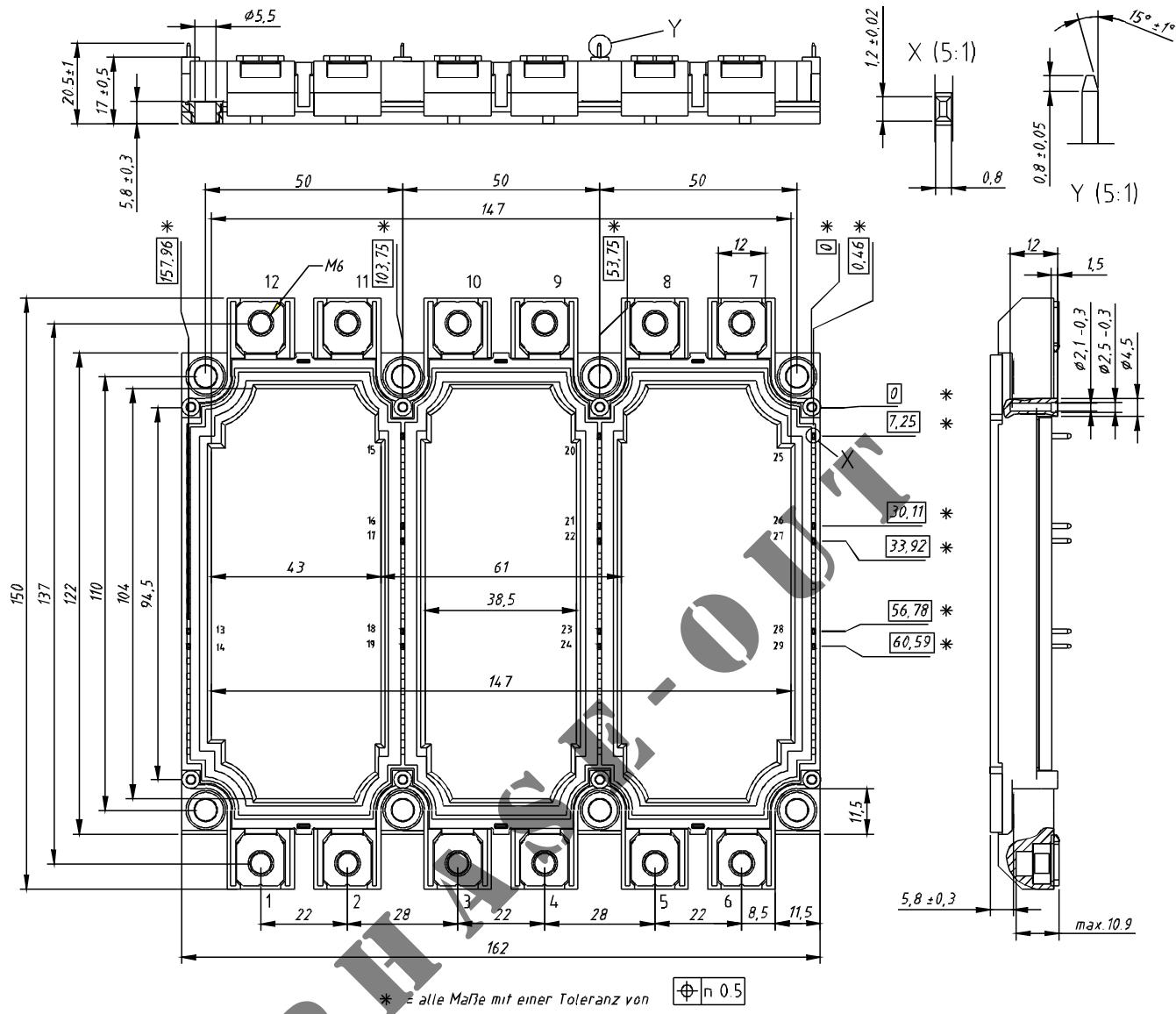
Module

Symbol	Conditions	Maximum Ratings		
T_{VJ}	operating	-40...+125		$^\circ\text{C}$
T_{JM}		+150		$^\circ\text{C}$
T_{stg}		-40...+125		$^\circ\text{C}$
V_{ISO}	$I_{ISO} \leq 1 \text{ mA}; 50/60 \text{ Hz}$	3400	V~	
M_d	Mounting torque (M5) Terminal connection torque (M6)	3 - 6	Nm	
		3 - 6	Nm	

Symbol	Conditions	Characteristic Values		
		min.	typ.	max.
$R_{therm-chip}^{*)}$	Resistance terminal to chip		0.55	$\text{m}\Omega$
d_s	Creepage distance on surface	12.7		mm
d_A	Strike distance in air	10		mm
R_{thCH}	with heatsink compound		0.01	K/W
Weight			900	g

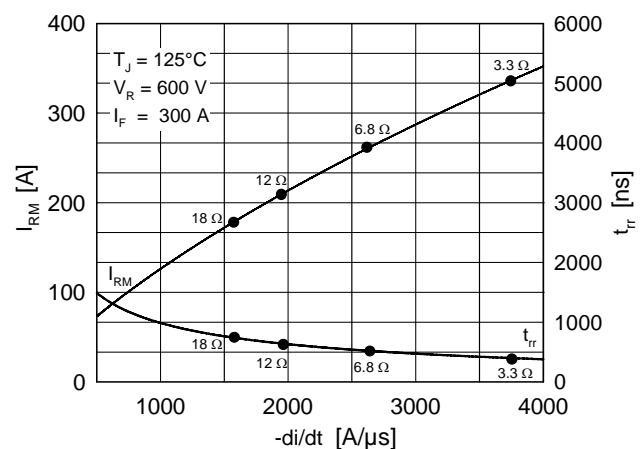
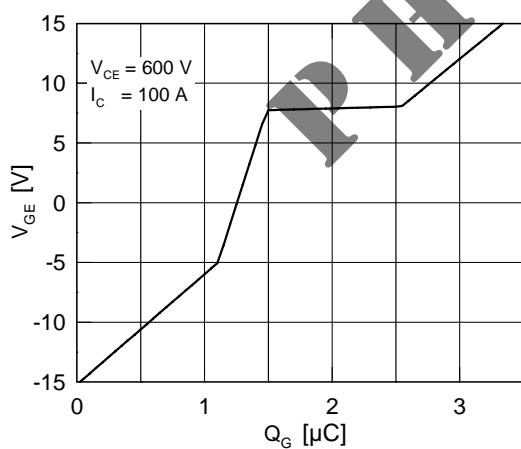
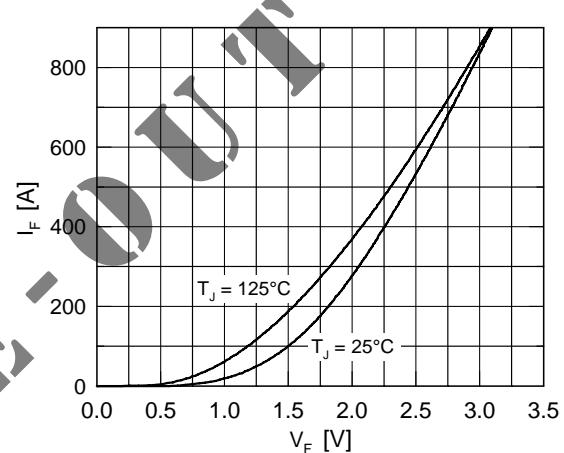
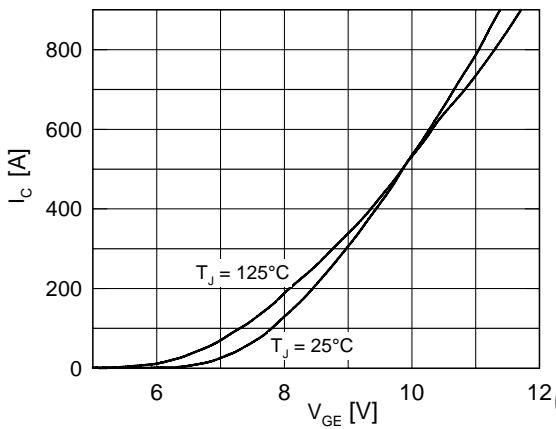
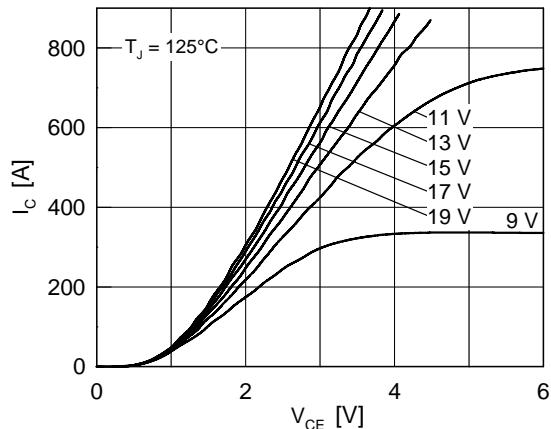
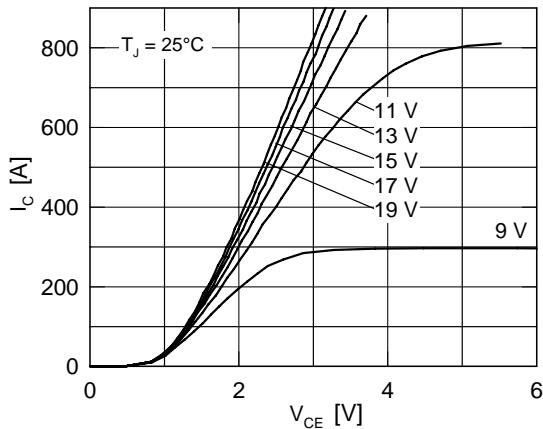
 $^{*)} V = V_{CESat} + 2 \times R_{therm-chip} \cdot I_C \text{ resp. } V = V_F + 2 \times R \cdot I_F$

Dimensions in mm (1 mm = 0.0394")



= tolerance for all dimensions:

Diode		IGBT	
R_i	τ_i	R_i	τ_i
$2.884 \cdot 10^{-5}$	$1 \cdot 10^{-5}$	$2.344 \cdot 10^{-5}$	$1 \cdot 10^{-5}$
$1.523 \cdot 10^{-3}$	$5 \cdot 10^{-5}$	$5.97 \cdot 10^{-4}$	$5 \cdot 10^{-5}$
$7.617 \cdot 10^{-3}$	0.012	$5.97 \cdot 10^{-3}$	0.015
0.03	0.078	0.023	0.075
0.036	0.82	0.028	0.69



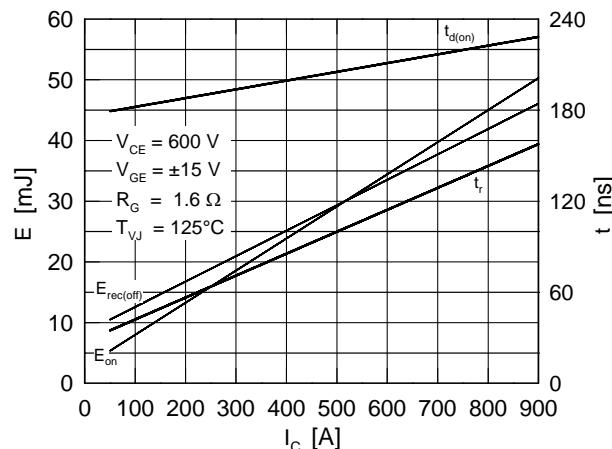


Fig. 7 Typ. turn on energy and switching times versus collector current

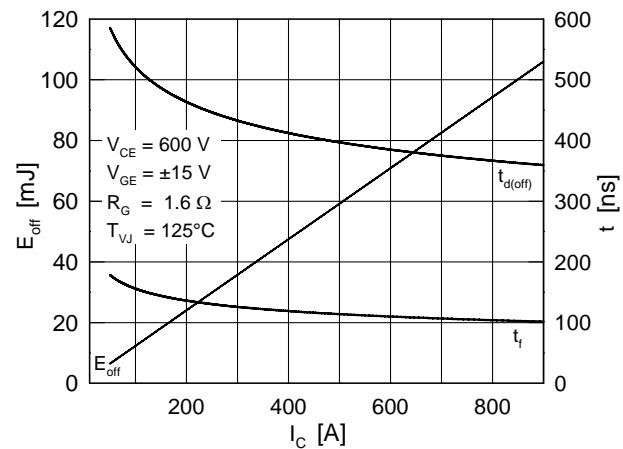


Fig. 8 Typ. turn off energy and switching times versus collector current

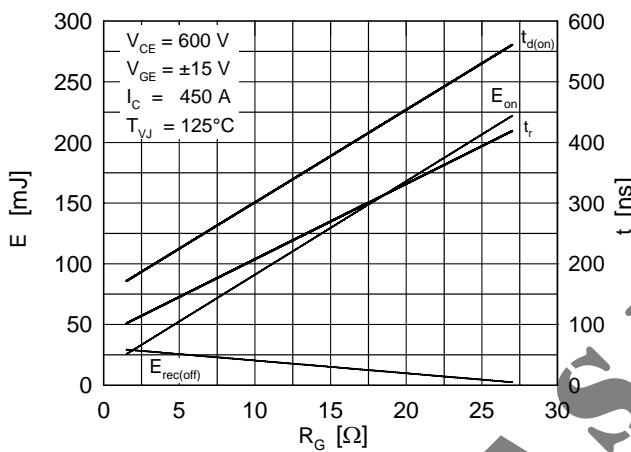


Fig. 9 Typ. turn on energy and switching times versus gate resistor

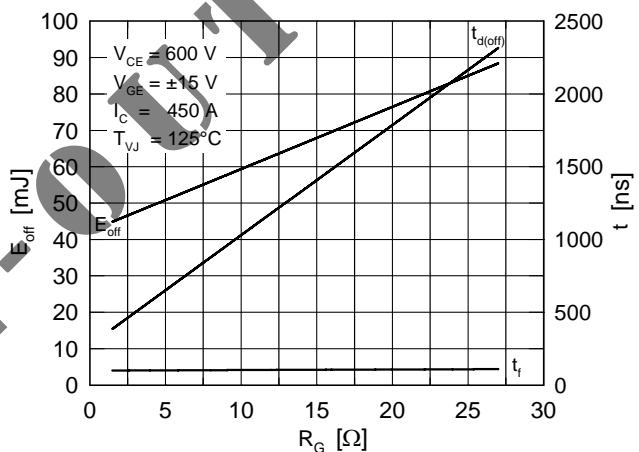


Fig. 10 Typ. turn off energy and switching times versus gate resistor

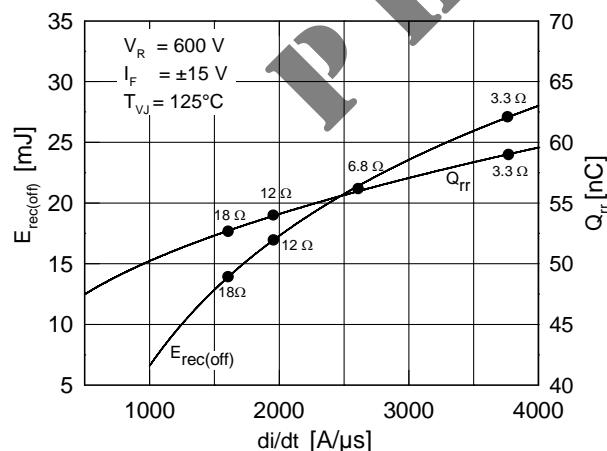


Fig. 11 Typ. turn off energy and recovered charge of free wheeling diode

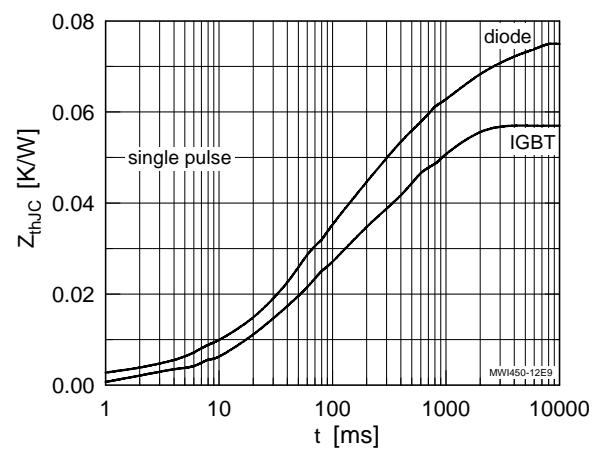


Fig. 12 Typ. transient thermal impedance